

# Tree Structure Based Algorithm for Multiobjective Optimization of Switch Allocation in Radial Distribution Networks

Zbigniew Galias

Department of Electrical and Power Engineering  
AGH University of Science and Technology, Kraków, POLAND

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- Reducing the consequences of outages in power distribution networks can be achieved by the installation of **sectionalizing switches**.
- Various objectives are used to optimize positions of switches, for example
  - the System Average Interruption Frequency Index (SAIFI),
  - the System Average Interruption Duration Index (SAIDI),
  - the Average Energy Not Supplied (AENS).
- Optimization of one of the objectives is often not equivalent to the minimization of another one.
- Goal: **Development of a fast algorithm to simultaneously minimize several reliability factors in single-feeder distribution networks with a radial topology.**

# Assumptions and notations

- The distribution network with a tree structure:
  - $V = \{v_1, v_2, \dots, v_m\}$  is the set of **distribution** and **load nodes**,
  - the **supply node**  $v_{m+1}$  is the **root** of the tree,  $n = m + 1$ ,
  - load nodes are **leaves**,
  - $c_j$  is the **connection line** between  $v_j$  and its parent,
  - $C_j$  is the set of indexes of **children** of  $v_j$ .
  - $D_j$  is the set of indexes of **descendants** of  $v_j$ .
- Distribution network parameters:
  - $N_j \geq 0$  is the **number of users** of the node  $v_j$ ,
  - $P_j \geq 0$  is **average active power** of the node  $v_j$ .
  - accumulated values:  $\bar{P}_j = P_j + \sum_{i \in D_j} P_i$ ,  $\bar{N}_j = N_j + \sum_{i \in D_j} N_i$ ,
  - $\lambda_{v_j}$  and  $\lambda_{c_j}$  are the **average failure rates** of the node  $v_j$  and the line segment  $c_j$ ,
  - $t_{v_j}$  and  $t_{c_j}$  are the **average total duration of failures** during one year  $v_j$  and  $c_j$ ,
  - $\lambda_j = \lambda_{v_j} + \lambda_{c_j}$ ,  $t_j = t_{v_j} + t_{c_j}$ ,
  - accumulated values:  $\bar{t}_j = t_j + \sum_{i \in D_j} t_i$ ,  $\bar{\lambda}_j = \lambda_j + \sum_{i \in D_j} \lambda_i$ .

# Objective functions: SAIFI, SAIDI, and AENS

- System Average Interruption Frequency Index (SAIFI),

$$\text{SAIFI} = \frac{\sum_{j=1}^m \mu_j N_j}{\sum_{j=1}^m N_j},$$

$\mu_j$  is the average number of interruptions.

- System Average Interruption Duration Index (SAIDI)

$$\text{SAIDI} = \frac{\sum_{j=1}^m U_j N_j}{\sum_{j=1}^m N_j},$$

$U_j$  is the average total duration of all interruptions involving the node  $v_j$  during one year.

- Average Energy Not Supplied (AENS)

$$\text{AENS} = \sum_{j=1}^m U_j P_j.$$

# Multiobjective optimization problem

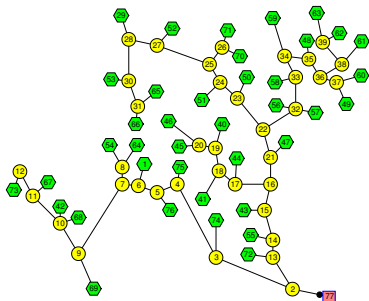
- The number of switches to be allocated is  $p$ .
- There are  $m$  admissible positions of switches.
- The search space:  $X = \{Q \subset \{1, 2, \dots, m\} : \#Q = p\}$ .
- $R_j$  is the set of switches in  $Q_j = Q \cap D_j$  with a path from  $v_j$  not passing through another switch.
- SAIFI( $Q$ ), SAIDI( $Q$ ), and AENS( $Q$ ) are the objectives for the case when switches are at positions in the set  $Q$ :
- A dominated solution is a solution, which is worse than another solution for each objective function.
- The set of non-dominated solutions is called the Pareto front:  $X_P = \{Q \in X : Q \text{ is non-dominated}\}$ .
- Multiobjective optimization problem: For given  $p$  find all non-dominated solutions with  $p$  sectionalizing switches.

# Tree structure based algorithm

- The algorithm is based on the single-objective tree structure optimization algorithm.
- Outline of the algorithm:
  - Visit nodes following the tree structure from leaves to the root node and construct partial solutions.
  - Partial solutions for a given node are constructed based on partial solutions found previously for its children.
  - The partial solution  $s$  generated by  $Q$  at the position  $j$  is the set of switches  $Q_s = Q \cap (\{j\} \cup D_j)$ .
  - For each partial solution compute gains in all objective functions obtained for this partial solution.
  - At each node compare partial solutions and skip those which cannot lead to a non-dominated solution (to prevent from the exponential growth of the number of partial solutions).
  - At the root node from the set of complete solutions select non-dominated solutions.

# Test distribution network

- A real network with from the southern part of Poland:
  - $m = 76$  line segments,
  - 39 load nodes,
  - 37 distribution nodes,
  - a single supply node.



- Failure rates (data provided by the electricity company):
  - 3.1 faults in one year for every 100 km of a line segment,
  - $\lambda_{C_j} = 3.1 \times 10^{-5} l_j$  for a line segment with the length  $l_j$ ,
  - $\lambda_{V_j} = 0.03$  for user nodes,
  - $\lambda_{V_j} = 0.002$  for distribution nodes.
- Average fault durations:
  - $\tau_{C_j} = 0.983$  h for line segments,
  - $\tau_{V_j} = 1$  h for user nodes,
  - $\tau_{V_j} = 0.5$  h for distribution nodes.

# Computational complexity

- Computation times (in seconds, 3.4 GHz processor) to find the complete Pareto front using the the tree structure based algorithm (TS) and the exhaustive search method (ES).

| $p$ | ES      | TS   |
|-----|---------|------|
| 1   | 0.00    | 0.00 |
| 2   | 0.04    | 0.01 |
| 3   | 0.57    | 0.01 |
| 4   | 8.70    | 0.01 |
| 5   | 124.94  | 0.01 |
| 6   | 1706.25 | 0.02 |
| 7   |         | 0.02 |
| 8   |         | 0.04 |
| 9   |         | 0.05 |
| 10  |         | 0.07 |
| 11  |         | 0.07 |
| 12  |         | 0.08 |
| 13  |         | 0.10 |
| 14  |         | 0.08 |

- The ES method works only for  $p \leq 6$  (the computation time grows exponentially with  $p$ ).
- The results obtained using both methods are the same (for  $p \leq 6$ ).
- Finding all non-dominating solutions for  $p \leq 14$  using the TS algorithm takes a fraction of a second.

- **Conclusion:** the proposed multiobjective optimization algorithm is very efficient.



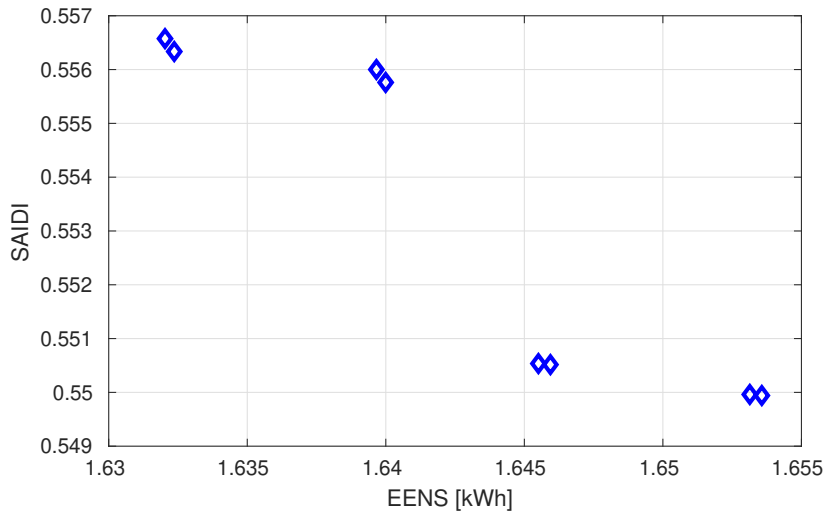
# Optimization results

- Pareto front sizes for various combinations of objective functions:

| $p$ | AENS  | AENS  | SAIDI | AENS  |
|-----|-------|-------|-------|-------|
|     | SAIDI | SAIFI | SAIFI | SAIDI |
|     | SAIFI |       |       | SAIFI |
| 1   | 3     | 3     | 1     | 3     |
| 2   | 3     | 3     | 1     | 3     |
| 3   | 2     | 2     | 1     | 2     |
| 4   | 1     | 1     | 1     | 1     |
| 5   | 1     | 1     | 1     | 1     |
| 6   | 2     | 2     | 1     | 2     |
| 7   | 2     | 2     | 1     | 2     |
| 8   | 4     | 4     | 1     | 4     |
| 9   | 8     | 6     | 2     | 8     |
| 10  | 6     | 3     | 2     | 6     |
| 11  | 4     | 1     | 4     | 4     |
| 12  | 6     | 3     | 2     | 6     |
| 13  | 4     | 2     | 2     | 4     |
| 14  | 4     | 2     | 2     | 4     |

- In most cases the Pareto front is nontrivial—contains more than one element (neither solution can be considered to be optimal for all objective functions simultaneously).

# Example: the Pareto front for the AENS/SAIDI multiobjective optimization problem, $p = 9$



# Conclusions

- A tree structure based algorithm to solve the switch allocation problem with multiple objectives has been proposed.
- The algorithm has been tested using a network of a moderate size showing its high efficiency.
- Multiobjective optimization may be useful in the design and modernization of distribution networks.